Engine ingestion as a result of crosswind during take-offs from water contaminated runways

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Executive summary

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The method, named ‘CRspray’, has been validated using laboratory and flight test experiments. Contaminated runway drag and ingestion can be determined depending on the pool depth, wind conditions, aircraft geometry, tyre geometry and pressure, aircraft weight, the wing lift and the horizontal tail plane vertical force.

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Abstract

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This paper deals specifically with crosswind-effects on the spray. Crosswind may lead to high engine water ingestion rates, exceeding ingestion limits. This may cause engine performance decrease, but at excessive ingestion quantities also surge, stall or even flame-out may occur. The airworthiness requirements state that an airplane may not ingest hazardous quantities of water or slush into engines and APUs during take-off, landing and taxiing. Therefore, evaluating the crosswind effects on contaminated runway operation is inevitable.
1 Introduction

A runway is considered contaminated by water if more than 25% of the used runway surface contains water with a pool depth of at least 3 mm. For airworthiness certification, pool depths up to 15 mm to 19 mm are considered \cite{1},\cite{2},\cite{3},\cite{4}. An aircraft taking off from a runway contaminated by standing water experiences both increased drag due to the displacement of the water by the tyres and due to the impingement of the water spray on the aircraft. This will result in a longer take-off run.

A good aircraft design avoids engine water ingestion. However, cross wind may deflect the spray towards the engine intake. In adverse conditions crosswind may lead to high engine ingestion rates, exceeding engine ingestion limits. This may not only cause engine performance decrease, but at excessive ingestion quantities also surge, stall or even flame-out may occur. As the aircraft already experiences an increased precipitation drag it is clear that performance degradation or even the loss of an engine in this situation is critical. The airworthiness requirements state that an airplane engine or APU may ingest water but not in hazardous quantities during takeoff, landing and taxiing and that crosswind effects have to be examined in order to specify crosswind operation limitations to be included in the flight manual.

Therefore it is advisable to get a good impression of the properties of a given aircraft design both in terms of precipitation drag and engine water ingestion. This may affect the choice of undercarriage configuration, tyres, the shape of the fuselage belly or, even, the engine position.

Some simple methods \cite{1}, \cite{5} exist to give an estimate of the precipitation drag. However, these methods are only capable of giving a first rough estimate of the location of the spray and the magnitude of the precipitation drag. Also the spray location is only roughly predicted and no information can be obtained on water flow rates and engine water ingestion levels. Moreover, cross wind effects cannot be determined.

This fact urged the development of a more advanced method for prediction of the water contamination effects on aircraft performance. Therefore NLR developed a method called ‘CRspray’ (‘Contaminated Runway Spray’). The method is based on water droplet trajectory calculations. The calculation uses a Monte-Carlo simulation and starts from basic principles supplemented with empirical data. The method has been validated using laboratory and flight test results.

This approach allows to vary parameters that affect the spray development and – as a consequence – airplane performance and safety. Among those is the effect of crosswind. Normally, pool tests are only performed for the prevailing wind conditions. As the location of the spray sometimes is critical as far as engine ingestion is concerned, this does not give unambiguous information on the risks of engine ingestion in case of (different) crosswind conditions. Moreover, weather conditions provoking runway flooding will often go together with strong wind conditions. Therefore it is inevitable to study the effects of wind on the spray development and ingestion risk.

The paper starts with a description of the method. Next, some validation results will be shown. Also the effect of changing some of the discussed aircraft parameters is focused on. Finally, the effects of crosswind on the spray will be highlighted for a typical aircraft configuration.
2 Spray pattern calculation

CRspray assumes the spray to be composed of a large number of single droplet trajectories. In order to start the trajectory calculation, initial values of particle properties: velocity vector, particle diameter and location are required. The initial properties are derived from empirical data available for water sprays, mainly the rudimentary ESDU spray description [5], on one hand and on basic, physical principles on the other hand.

A tyre rolling through a water pool develops a wave front because the water is washed away from the tyre track (figure 1). If this happens with sufficient speed, the resulting wave contains enough energy, such that the water surface tension can no longer keep the wave integrated and particles start to separate into a spray. In front of the tyres a bow wave develops, ejecting spray in forward and upward direction. Besides the tyres a straight side wave front develops, ejecting the spray sideways and upward. For side-by-side tyres the sideways wave fronts in between the tyres merge and a single straight center-wave front develops from which the spray emerges in vertical direction.

The initial conditions are derived partly from the ESDU spray model. This model is too concise, however, to derive all the initial quantities for the droplet trajectory calculation. Moreover, it does not contain the important bow wave in front of the tyres. Another limitation of the ESDU model is that it assumes a linear downstream spray development, which cannot be true for the actual spray as the vertical droplet velocity is not constant but changes due to gravity and aerodynamic resistance forces. Nevertheless, the ESDU data offer the advantage that spray-data of a relatively large number of different undercarriage and tyre combinations have been modeled. Therefore the ESDU data are used as a guide for the side wave front location and the initial velocity vector as well as the variance thereof. The latter two are determined indirectly from the spray envelopes available from the ESDU model. Other parameters (spray density, droplet size, bow wave properties) are modeled using spray data obtained by other researchers, both in model experiments ([6], [7], [8]) as well as flight tests by Dassault (Falcon 2000) [9], Saab (SAAB 2000) [10] and NLR (Cessna Citation II) [11],[12].

Large scale disturbances in the flow field, e.g. caused by the circulation around the wing generated by wing lift or the wind are taken into account. The same is done for the airflow generated by the spray itself as a result of air entrainment.
2.1 Main initial parameters
A short survey of the initial parameters used is given here:

Hydroplaning reference speed:
The hydroplaning speed is important as the shape of the spray, especially the bow wave part, is strongly affected at speeds approaching the hydroplaning velocity. As a reference for determining the hydroplaning speed the maximum drag speed as defined in the airworthiness regulations (AMJ 25X1591) is used:

\[ V_p = 17.6\sqrt{p_t} \]

\( p_t \) tyre inflation pressure in bar, \( V_p \) in m/s. The hydroplaning speed is taken as \( V_h = 1.07 V_p \).

Spray wave front location:
The location of the side wave front is related, but not equal to the position of the side wave front from the ESDU data as the ESDU data mainly focus on the most intense upper part of the spray and not on the ground bound part of the spray. This most intense part of the spray is represented by a parallelogram area, see figure 1. However, like ESDU does, the side wave front is assumed to be a straight line.

The bow wave front has an elliptical shape, with both halves split up by a straight connection in case of side-by-side tyres. On approaching the hydroplaning speed, the bow wave disappears. The centre wave front is a straight line, starting from the bow wave and running aft.

Particle initial velocity vector: The initial velocity vector is estimated, using the ESDU envelope as a starting point. Corrections are applied for the decay of the initial velocity at positions further downstream along the wave front.

Particle diameter:
The spray starts as a liquid sheet originating from the spray front. Such a sheet injected into a gaseous environment normally is unstable. Oscillation of this sheet and subsequent break-up lead to atomization. First liquid ligaments (primary break up) and then droplets (secondary break up) are formed. Disintegration of larger droplets continues till the droplets become small enough such that the surface forces keep the droplets intact ([13], [14]). Therefore, droplet breakup is characterized by the Weber number, representing the ratio of aerodynamic forces acting on the droplet to the stabilizing surface tension force.

\[ W_e = \frac{\rho_a V_R^2 D_p}{\sigma_p} \]

\( \rho_a \) equals the air density, \( V_R \) the particle slip velocity, \( D_p \) the particle diameter and \( \sigma_p \) the particle surface tension. If the \( W_e \)-number becomes smaller than a critical breakup value, droplets no longer disintegrate [13]. This value depends on the droplet slip velocity Reynolds number \( Re = (V_r D_p)/\nu_a \). Kolev [15] gives the following relation:

\[ W_{e_{cr}} = 55 \left( \frac{24}{Re} + \frac{20.1807}{Re^{0.613}} - \frac{16}{Re^{2/3}} \right) \]

This relation can be approximated very well on its validity range of 200<\( Re <2000 \) by the simpler expression:
\[ \text{We}_{bu} = \frac{671}{\text{Re}^{0.63}} \]

being used in CRspray. For \( Re > 2061 \), \( \text{We}_{bu} \) is taken equal to 5.48, the minimum value found for break up under sudden acceleration conditions. For \( Re < 200 \) the equation is no longer valid. In that range particle diameters tend to become very large. It is shown in the literature (e.g.\([16], [17]\)) that stable water droplets falling in air will likely break up if they become too large. The upper limit lies in the range of droplet diameters of 6 to 10 mm. Therefore, the maximum average particle diameter has been limited to 8 mm.

Whether or not viscosity is important in this process is determined by the Ohnesorge number,

\[ Oh = \frac{\mu_p}{\sqrt{\rho_p D_p \sigma_p}} \]

where \( \mu_p \) stands for the particle dynamic viscosity. A higher \( Oh \), i.e. viscosity, delays droplet breakup, resulting in a correction to \( We \) if \( Oh < 0.01 \) [14]. For the sprays studied here viscosity effects may be disregarded.

Many different droplet size distributions exist, often being slightly skewed towards higher droplet diameters ([18], [19]). Despite this, the main part of the droplet size distribution is Gaussian distributed. Therefore, CRspray applies the Gaussian distribution on \( D_p \) for simplicity.

**Atomization fraction**

Not all the water behind the wave front will be atomized. Part of it just moves sideways, especially further downstream. Therefore an atomization fraction parameter \( AF \) is introduced, being the ratio of water atomized by the wave front, relative to the total volume of water initially present in the same part of the pool through which that wave front passed. The local atomization fraction has been related empirically to the local Froude number and the local initial velocity magnitude. For this purpose the results obtained from laboratory tests ([6], [7] and [8]) have been used.

### 2.2 Calculation of the flow field

Particle sizes in the spray typically range from 0.5 to 10 mm. A measure for describing the ability of a particle to follow the flow is given by the particle inertia parameter:

\[ K = \frac{\rho_p D_p^2 V_R}{18 \mu_a c} \]

where \( \rho_p \) stands for the particle density, \( V_R \) equals the particle slip velocity, \( \mu_a \) the dynamic viscosity of air and \( c \) a reference length scale. The particle inertia is reflected in the particle equation of motion as follows, see e.g. [20):

\[ K \ddot{\xi} = \left( \frac{C_p \text{Re}}{24} \right) \tilde{\omega}_D + \left( \frac{K}{Fr^2} \right) \tilde{g} \]

with \( \ddot{\xi} = \frac{\ddot{r}}{c} \) being the dimensionless location vector, \( \tilde{\omega}_D \) the dimensionless particle slip velocity \( \frac{\dot{V}_R}{\text{Re}_r} \), \( \tilde{g} \) the gravitational vector and \( Fr \) the Froude number, \( \frac{\text{Re}_r}{\sqrt{g c}} \).

As described in [20], a study concerning the droplet collection efficiency of airfoils, particles no longer are able to follow the flow curvature close to wing leading edges for \( K > 1 \). For the sprays considered in the present study, typical values of \( K \) are
well above 1. This means that small scale velocity perturbations to the flow field need not be modeled, as the particles will not be able to respond to those. Therefore, it is not necessary to calculate the flow field around the airplane in detail. In the present model only the general circulation around the wing, the entrainment velocity generated by the spray and – evidently – the (cross)wind velocity have been modeled.

The effects of wing lift on the flow field were included by putting a vortex-sheet at the wing chord and calculating the resulting flow field induced by the lift generated circulation around the wing. The sheet, stretching from 5 to 75 percent of the local wing chord \( c \), has constant distributed vortex strength, such that the wing lift is represented correctly.

A large part of the spray passes underneath the wing. For a low-winged aircraft it is important to mirror the circulation into the ground surface, which increases the disturbance velocity especially below the wing. For e.g. the Cessna Citation, the ground surface is at around \( 1/3 \)rd of the wing chord below the wing. This will lead to an extended region with relatively low-speed air below the wing.

No interaction between the droplets constituting the spray has been assumed in the sense of droplet collisions. However, an indirect particle interaction has to be taken into account. This is the air entrainment velocity generated by the spray itself. This entrainment is caused by the drag forces acting on the separate droplets, resulting in the air in the vicinity of the spray to move in the same direction as the spray. This, in turn, reduces the slip velocity, sensed by the particles, and therefore lowers the drag forces on them. As a result the spray will rise higher. Because of the high spray density, the entrainment effect is significant. It is modeled, assuming that the air entrainment velocity is proportional to both the local particle density and the particle drag.

The (cross)wind velocity distribution with height in the atmospheric boundary layer is approximated by means of a 1/7\(^{th}\) power law distribution. The wind velocity at \( Z=10 \) m height is used as a reference:

\[
\frac{V_x}{V_{w,10}} = \left(\frac{Z}{10}\right)^{\frac{1}{7}}
\]

For tail mounted engines the main interest is in crosswinds towards the fuselage on the side of the engine under investigation and not away from the fuselage. Moreover, as cross wind velocities are in the order of 10 to 20 knots, and rolling velocities are a factor 2 to 10 higher, the angle between the effective wind direction and the fuselage axis remains relatively small. Therefore the effect of the fuselage on the cross wind field is not taken into account.

2.3 Aircraft modeling

If the spray hits the aircraft it is partially reflected. As the calculation of the flow field does not require a detailed modeling of the aircraft, only that part of the aircraft has to be modeled to some detail that can possibly be hit by the water spray in order to allow for the reflection and subsequent impingement drag calculation. A number of elementary ‘building blocks’ has been defined, like cylinders, flat surfaces, a fuselage fairing cross section, a wing like cross section, etcetera. This allows a quick representation of the shape of the aircraft in more or less detail, as desired. Some examples can be found in the sketches in this paper.
2.4 Precipitation drag

The precipitation drag consists of two main components, displacement drag and impingement drag. The first one is the result of the work performed by the tyres breaking their way through the water pool. The second drag force is a result of the spray impinging on and flowing along the airframe. The displacement drag is calculated using a slightly modified ESDU method [21]. The modification involves a $1/V^3$ decay at velocities above hydroplaning instead of the $1/V^2$- behavior as taken by ESDU. The modification is believed to better represent the available experimental data as the latter would result in a constant displacement drag, which is not confirmed by the experimental data. Besides, [21] shows a displacement drag error bandwidth of around 40%, which is substantial and leaves room for improvement.

To calculate impingement drag, the spray is considered to consist of separate particles that hit the aircraft. A partial elastic collision is assumed. Upon collision, the spray partly reflects off the surface. The remaining part adheres to the surface and forms a water film that flows aft over the aircraft. The two main forces that contribute to the impingement drag are the collision force occurring at the moment of reflection and the surface shear force caused by the water film flow along the surface. The collision force dominates at parts of the aircraft surface being normal to the direction of movement, like the wing leading edge. The water film shear drag force dominates at those parts of the surface being more or less horizontally. Although the contribution of the collision forces normally is larger, the water film shear force cannot be neglected, as will be shown later. Both drag contributions therefore have to be modeled. The method used for derivation of both forces has been explained in more detail in [22].
3 CRspray results

3.1 Validation

CRspray has been validated using both laboratory test cases as well as flight test results on a Cessna Citation II, the SAAB 2000 and the Dassault Falcon 2000. Also results obtained from a larger aircraft, the 100-seater Dassault Mercure, have been used. Comparisons with large transport type aircraft are still welcome to further validate the method for this category. Some results are shown here.

Figure 2 shows results for a laboratory test, performed in the Hydrodynamics Research Facility at NASA Langley. Ref. [6] describes a number of tests on two different types of tyres with varying tyre pressures and tyre loads. The figure shows the results for a 26 inch cross-ply tyre, inflated to 3.1 bar. The tyre load amounts to 6700 N and the pool depth equals 16 mm. The ground speed equals 12.2 m/s (40 ft/s), corresponding to almost 70% of the hydroplaning velocity at the given, relatively low, tyre
pressure. The parallelogram-shaped ESDU envelope is also shown in figure 2. In this calculation 5000 particle tracks are used. Note that there is some discrepancy between the measured spray and the ESDU-envelope. Possibly this is caused because the tyre pressure used in the experiment being only about 25% of the rated tyre pressure. A very reasonable comparison, not only in spray position, but also in spray density between CR\textit{spray} and the experiment is obtained.

A comparison between calculation and a flight test, conducted by NLR, with the Cessna Citation II aircraft is shown in figure 3. The main gear has a single 22x8 cross-ply tyre. The nose gear is equipped with a single 18x4.4 cross-ply tyre, provided with chines. The main gear tyre pressure equals 9.6 bar (140 psi), the nose gear pressure equals 8.4 bar (120 psi), resulting in hydroplaning velocities of 106 and 99 kts respectively, according to AMJ [1]. Aircraft speed was 80 kts, about 70 % of the hydroplaning speed. The pool depth equaled 12 mm.

During the flight tests, hydroplaning started to occur at speeds above 90 kts. Note that $V_p$ according to AMJ is not equal to the actual velocity above which initial signs of hydroplaning occur, but roughly corresponds to the velocity were maximum tyre displacement drag is found. For instance, data from Leland and Taylor [23] indicates that tyre spin down starts from a velocity of 8% below $V_p$.

Figure 4 shows the precipitation drag for this aircraft for the same pool depth (12 mm). In this case, the CR\textit{spray}-prediction is performed using 2000 particles for each side spray. A test has been done to calculate the drag with a varying number of particles and this learned that about 1000 particles per side spray are required to obtain a drag prediction accuracy within about 1% of the value obtained with a very large number of particles (10000). The figure shows that the predicted precipitation drag agrees well with the flight test data.

The figure also shows the AMJ [1] drag prediction that is assumed to be valid below hydroplaning (dashed line). This value is seen to be substantially lower than the flight test data. The AMJ drag prediction takes into account the displacement drag of each undercarriage and the impingement drag of the nose wheel by means of a relation between drag and wetted length of the fuselage. Apparently this relation is too crude.
The cause for this difference may be that the relation was derived using data from larger aircraft. It is recognized generally that traditional methods may underpredict precipitation drag especially for smaller jet aircraft.

The separate drag contributions (shear drag, collision drag and displacement drag) are shown as well. The nose gear is the main contributor to the collision drag as much of this spray hits the lower side of the fuselage and the wing leading edges. It is seen that the shear drag cannot be neglected. It amounts to about 2/3rd of the collision drag.

As soon as hydroplaning becomes apparent (above 80 kts), the spray flattens and the magnitude of impingement on the aircraft reduces significantly. Here the drag consists almost exclusively of displacement drag.

CRspray enables studying the effect of changing some parameters on the precipitation drag. The influence of wing lift is shown here. For the Citation normally $C_L=0.4$ is assumed during the take-off run. A calculation has been performed for zero lift as well. This increases the tyre load, and reduces the induced velocity field around the wing. Figure 5 shows the effects on the drag. It is clear that the differences increase with velocity as the wing lift develops. The higher tyre load results in a more dense spray and therefore higher precipitation drag. The maximum contamination drag increases to around 7000 N. The figure contains some flight test data points obtained with zero flaps. For the Citation II it is estimated that this results in a drop in wing $C_L$ of around 0.5, compared to a flap setting of 15° that was used with the other test points. Therefore it seems that the lift effects on the contamination drag are predicted reasonably well.

Earlier it was mentioned that the particle sizes in the spray are typically in the range between 0.5 and 10 mm. Figure 6 shows the particle size distribution for the spray of the Citation at 4 different cross sections between stations just in front of the wing ($X=4.27$, see figure 3 for the X-positions) and at the tail of the aircraft ($X=12.8$). The majority of particle sizes lies around 1 mm. A second ‘hump’ occurs at particle sizes around 8 mm. The smallest particles are generated in the bow wave in front of the tyre as the atomization effect is largest here.

The larger particles are generated at increasing distance behind the tyre. This explains the maximum found for $X=6$. At the tail position, part of these particles have fallen back to the ground, not alone due to particle weight, but also due to their low initial velocity. This reduces the number of large particles counted in this cross section. Most particles reaching the engine originate from the bow wave and initial side wave region and therefore are of order 1 mm in size.

![Figure 6: Typical distribution of particle size at 4 X-positions (Citation, 60 kts, nose tyre spray)](image)
3.2 Engine ingestion

To obtain sufficient accuracy for engine ingestion, more particles are required for the simulation than is the case for precipitation drag. Figure 7 shows the dispersion in ingestion level for a varying number of particles. This result is obtained for a generic executive aircraft, slightly larger than the Citation and comparable e.g. to the Falcon 2000. This generic aircraft is designated ‘CRA’ (Contaminated Runway Aircraft). The figure shows that 5000 particles per side spray are required to obtain ingestion values within 1 kg/s or 7% of the average value. All calculations for this aircraft have therefore been performed with this number of particles.

The aircraft is equipped with side-by-side tyres both for the nose gear as well as for the main gear. The nose gear has 14.5x5.5 tyres without chines; the main gear has 26x6.6 tyres. All tyres are cross-ply and the distance between the pair of nose tyres and main tyres amounts to 0.24 m and 0.30 m respectively. The nose and main tyre are inflated to 11.1 and 13.5 bar respectively. Aircraft weight equals 20000 lbs.

Figure 8 shows a typical spray pattern around the CRA aircraft from two different viewing angles. Dimensions along the axes are in meters. The reflection of the spray on the wing is clearly visible. Pool depth used for the CRA equals 15 mm. Only the nose gear is causing ingestion. The spray from the main gear does not reach the engine, due to the shielding effect of the wing. Therefore this part of the spray is not shown. The pink trajectories are those that are ingested by the engine. Note that only a limited number of the actual 5000 trajectories being calculated is shown in these figures for clarity.
Fig. 9: CRA: flow distribution for the same case as above in the engine intake cross section

The ingestion for this aircraft is drawn against rolling velocity for the case without cross wind in figure 10. Both the results for tyres with and without chines are shown. It is seen that the aircraft is not completely free of ingestion, even with chines. Without chines, the ingestion level goes up to 3.3 kg/s. This maximum is reached at a rolling velocity of 65 kts. At 50 kts and below the core of the spray passes outside of the engine intake. At velocities above 80 kts, gradually hydroplaning effects set in, limiting the height the spray reaches. In that case the ‘core’ of the spray passes just below the engine intake. The hydroplaning velocity for the nose tyre is indicated in the graph by the red dot.

Of course the question remains what levels of ingestion are acceptable. This depends on the engine characteristics and will be specified by the engine manufacturer. A typical engine in the ‘CRA category’ could be the TFE-731 having a maximum thrust of 16.5 kN. This thrust corresponds to a mass flow of around 55 kg/s. In flight engine operation requirements typically specify a water/air ingestion mass flow ratio of 4% at which no hazardous loss of power may occur (e.g. [3]). This corresponds to a safe ingestion limit of 2.2 kg/s.

The dimensionless flow distribution levels (m³/s/(m².m/s)) in the spray at the position of the engine intake are shown in figure 9. The engine intake cowl highlight is shown as a grey circle in the figure. It is seen that the ingestion levels for this case (with a slight cross wind) reach around 14 kg/s, which is appreciable. The total water flow in the spray through this cross section amounts to about 50 kg/s. The flow pattern also nicely shows the ‘shadowing’ effect by the wing.

Fig. 11: CRA: ingestion rates as function of cross wind velocity for various rolling speeds
3.3 Crosswind effects

The question arises whether crosswind may affect the position of the spray in such a way that ingestion is increased significantly. If a crosswind occurs, the resulting ingestion rates for the generic CRA geometry are shown in figure 11. Negative values of Vx correspond to a crosswind forcing the spray towards the fuselage-mounted engine.

Without cross wind the ingestion remains relatively limited to around 3 kg/s at ground speeds of 60 to 70 kts, as shown before. These levels quickly increase for negative cross winds. The maximum ingestion occurs for a speed of 60 kts and amounts to almost 17 kg/s. In view of the acceptable ingestion limit of 2.2 kg/s, this ingestion rate will almost certainly be unacceptable for the engine. For lower speeds the required crosswind to obtain maximum ingestion becomes larger. In that case the spray is located more outboard and therefore a stronger crosswind is required to cause ingestion. Figures 12 and 13 show the flow distributions in the various sprays in a cross section coinciding with the engine intake.
By deflecting the elevator, the loading on the nose wheel may be lowered, thus reducing the intensity of the spray generated by the nose tyre. This may have a favorable effect on the engine ingestion. Therefore this case was also calculated. It is assumed that the upward elevator deflection results in a $C_{L,h}$ of -1 on the horizontal tail plane. This may be considered a fairly high value. It is seen that the upward deflection of the elevator unloads the nose gear and results in a reduction of the ingestion to about 12 kg/s maximum. Vice versa a downward deflection causes additional loading of the nose gear and results in an increase in ingestion to about 20 kg/s. The same happens if the wing lift is eliminated (figure 14). Also, in those cases the maximum ingestion also occurs already at lower cross wind velocities.

Often nose tyres are equipped with chines. In case of chines the ingestion rates become lower and also the maximum ingestion occurs at higher crosswind velocities. Figure 15 shows the results for a ground speed of 60 kts. Therefore, in practice, an aircraft like the CRA will almost certainly be equipped with chines. Note that without crosswind the ingestion rate with chines equals almost zero. However, if crosswind sets in, ingestion occurs also with chines. This means that an ingestion free test at zero crosswind does not guarantee that ingestion does not occur for unfavorable crosswinds!

This should be born in mind when judging water trough tests. A thorough evaluation of crosswind risks cannot be circumvented.

**Fig. 14: CRA: effect of elevator up deflection on ingestion rates**

**Fig. 15: CRA: ingestion lowered by nose tyre equipped with chines, ground speed 60 kts.**
4 Conclusion

A method for calculating the effect of a water spray generated by tyres on a contaminated runway has been developed. The method allows calculating the effects of various parameters on the aircraft drag and engine ingestion and has proven to be a useful tool for this purpose. It is shown that crosswind may give rise to high engine ingestion levels, depending on the aircraft ground speed. High engine ingestion may lead to a flame-out in the worst case and represents a critical situation, especially as precipitation drag is already extending the take-off roll. For tail mounted engines the windward engines will be at risk in this respect. It is also shown that zero ingestion at low wind speeds in no guarantee for low ingestion at even moderate crosswind velocities.

References


